

Gromov-Wasserstein Bound between Reeb and Mapper Graphs

XVII CLAPEM

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Background

Reeb Graph

Let X be a topological space and let $f : X \rightarrow \mathbb{R}$ be a continuous function called *filter function*.

Let \sim_f be the equivalence relation between two elements x and y in X defined by:
 $x \sim_f y$ if and only if x and y are in the same connected component of $f^{-1}(z)$ for some z in $f(X)$.

The Reeb graph R of (X, f) is defined as the quotient space X / \sim_f .

Reeb Graph example

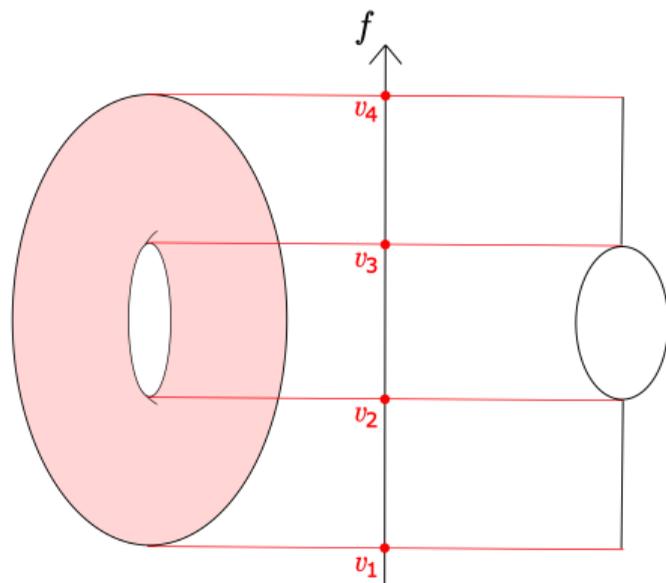


Figure: Example of a Reeb graph of a torus with the height function.

Mapper Algorithm

Given a sample $X_n = \{X_1, \dots, X_n\}$, taken from a topological space X as well as a filter function f :

1. Cover the range of values $Y_n = f(X_n)$ with a set of consecutive intervals I_1, \dots, I_r that overlap.
2. Group the points that fall in the same connected component of each preimage $f^{-1}(I_j)$. This defines a *pullback cover* \mathcal{C} of X_n .
3. The Mapper graph \mathbb{M}_n is defined as the *nerve* of \mathcal{C} .

Mapper Example

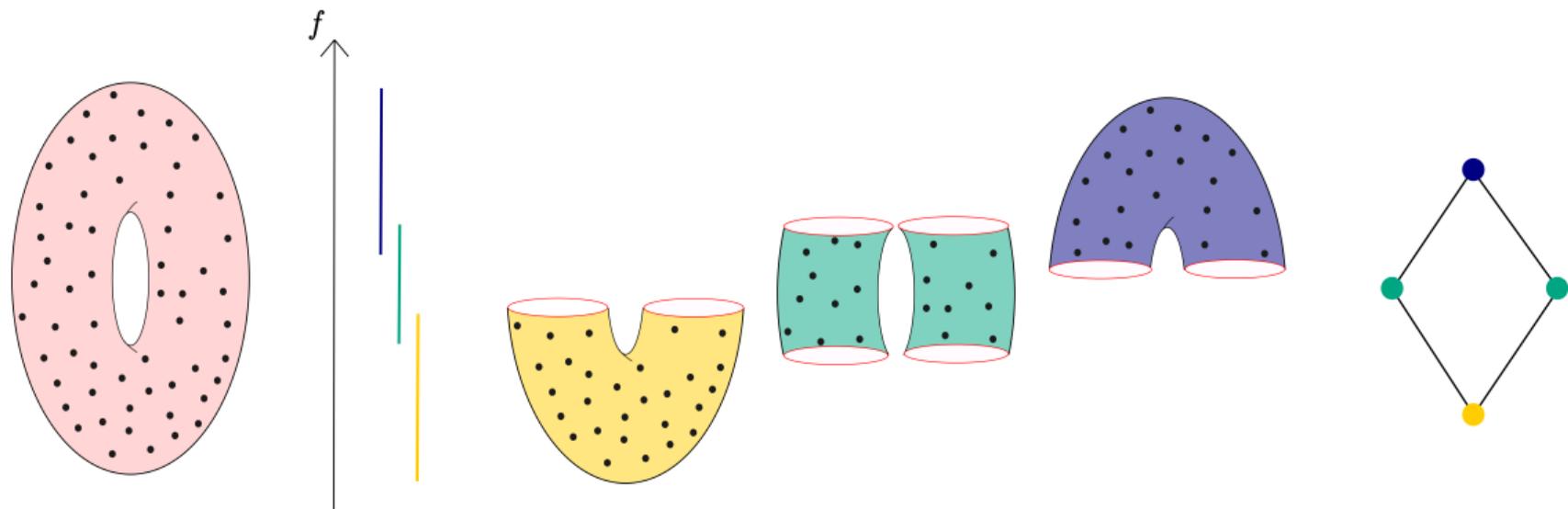


Figure: Example of a Mapper graph built on a torus.

Question

As n (sample size), r (resolution) $\rightarrow \infty$:

$$\|d\|(\mathbb{R}, \mathbb{M}_n) \rightarrow 0.$$

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$$"d" (\mathbb{R}, \mathbb{M}_n) \rightarrow 0.$$

- "d"?
- Relationship between r and n ?
- X_n is random. Probabilistic result ?

Existing approach: Cosheaves [De Silva et al., 2016]

A reeb graph is a covariant functor $F: \mathbf{Int} \rightarrow \mathbf{Set}$.

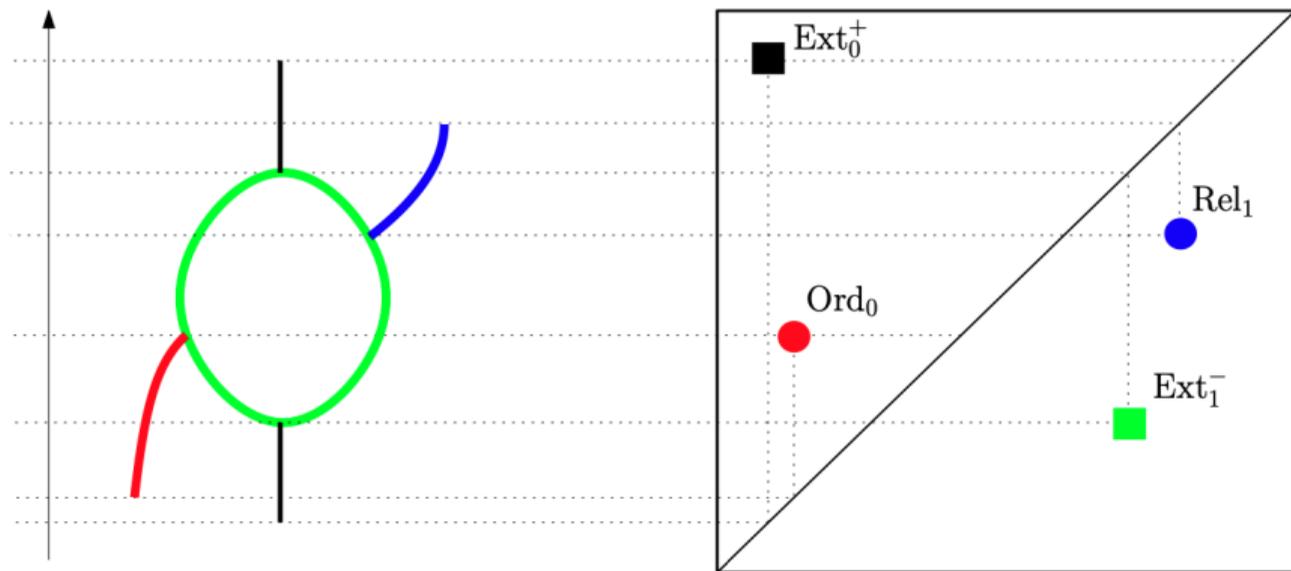
- $F(I) = \pi_0(f^{-1}(I))$
- $F(I \subseteq J) = \pi_0(f^{-1}(I) \subseteq f^{-1}(J))$

ϵ -interleaving:

$$\begin{array}{ccccc} F(I) & \longrightarrow & F(I^\epsilon) & \longrightarrow & F(I^{2\epsilon}) \\ & \searrow & \nearrow & \searrow & \nearrow \\ & & \varphi_I & & \varphi_{I^\epsilon} \\ & \nearrow & \searrow & \nearrow & \searrow \\ G(I) & \longrightarrow & G(I^\epsilon) & \longrightarrow & G(I^{2\epsilon}) \\ & \searrow & \nearrow & \searrow & \nearrow \\ & & \psi_I & & \psi_{I^\epsilon} \end{array}$$

- Stable w.r.t. function perturbations
- Similar approach possible for the Mapper

Existing approaches 2: Homology [Carrière and Michel, 2022]



Goal

Metric that incorporates measure information directly. (Also computable if possible...)

Metric Measure Space geometry

Metric Measure Space

A metric measure space (or mm-space for short) is a triple (X, d, m) where:

- (X, d) is a polish metric space, that is complete and separable,
- m is a measure on the Borel σ -algebra of (X, d) that is locally finite.

Gromov-Wasserstein distance

Gromov-Wasserstein distance

The Gromov-Wasserstein p -distance between two mm-spaces (X_1, d_1, m_1) and (X_2, d_2, m_2) is defined as:

$$\text{GW}_p((X_1, d_1, m_1), (X_2, d_2, m_2)) = \left(\inf_{d, \mu} \int_{X_1 \times X_2} d(x, y)^p d\mu(x, y) \right)^{\frac{1}{p}},$$

where the infimum is taken over all measures μ on $X_1 \times X_2$ that have marginals m_1 and m_2 , and on all metric couplings d of d_1 and d_2 .

Isomorphy between mm-spaces

If $\text{GW}_2((X_1, d_1, m_1), (X_2, d_2, m_2)) = 0$ (and under some assumptions), there exists a map $\Phi: \text{supp}(m_1) \rightarrow \text{supp}(m_2)$ such that:

- Φ is an isometry of metric spaces,
- $m_2 = m_1 \circ \Phi^{-1}$.

Reeb graphs as MM-spaces

In all of the following M is a compact connected Riemannian manifold and f is a Morse function.

We want to look at the Reeb graph $\mathbb{R} := \mathbb{R}(M)_f$ as a metric measure space

Why a Morse function ?

A smooth map $f : M \rightarrow \mathbb{R}$ is called a Morse function if its critical points are non-degenerate.

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Morse Lemma

Let $f : M \rightarrow \mathbb{R}$ be a Morse function and $c \in \text{Crit}(f)$. Then there exists a chart $\varphi : U \subseteq M \rightarrow \mathbb{R}^d$ containing c such that for every $p \in U$:

$$f(p) = f(c) - \sum_{j=1}^i x_j^2 + \sum_{j=i+1}^d x_j^2,$$

where $x = \varphi(p)$ and the integer i depends only on the signature of the Hessian at the critical point c .

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- $\text{Crit}(f)$ is finite.
- Level sets are locally path connected.

Cylinders

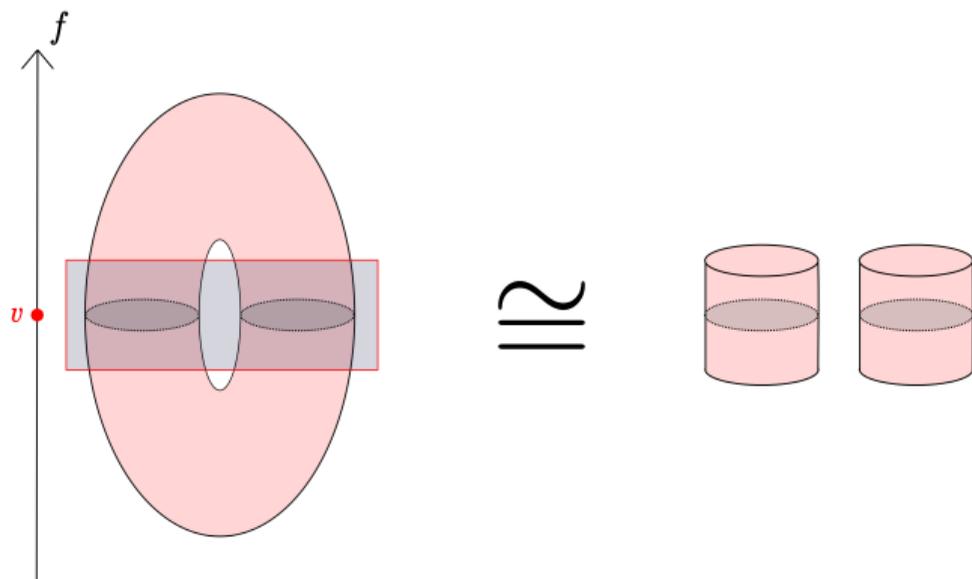


Figure: Around a non-critical value v , the manifold is homeomorphic to a finite collection of cylinders, whose faces are given by the level set $f^{-1}(\{v\})$.

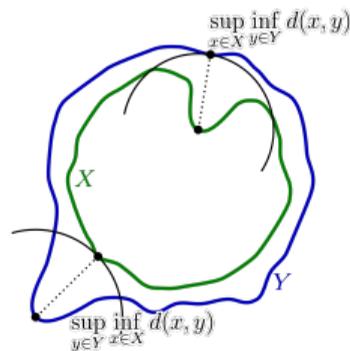
Hausdorff distance

Definition

Let A, B be two subsets of a metric space (X, d) , the Hausdorff distance between A and B is defined as:

$$d_H(A, B) = \max \left(\sup_{x \in A} d(x, B), \sup_{y \in B} d(y, A) \right),$$

where $d(x, B) = \inf_{v \in B} d(x, v)$ and $d(y, A) = \inf_{u \in A} d(u, y)$.



Hausdorff distance property

Proposition

When (X, d) is complete (resp. compact), then $(C(X), d_H)$ is complete (resp. compact).

For Reeb graphs

- The elements of \mathbb{R} are closed in M . (\mathbb{R}, d_H) is therefore a metric space.
- (\mathbb{R}, d_H) is however not closed, and hence not polish...

Not closed

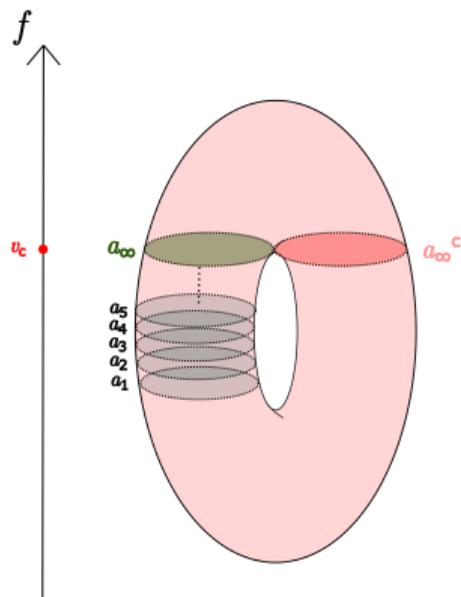


Figure: Example of a Reeb graph sequence $(a_n)_{n \in \mathbb{N}}$ that has a Hausdorff limit a_∞ outside of the Reeb graph. Notice that this occurs when a_∞ is inside the level set of a critical value v_c .

Topology of (\mathbb{R}, d_H)

Proposition

Let a be a compact subset of M that is an adherent point to R . Then a is connected and f is constant on a .

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π is Borel measurable.

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Proposition

$\bar{R} \setminus R$ is finite.

Comparison with the Mapper graph - Main result

What we showed

$(\bar{\mathbb{R}}, d_H, m \circ \pi^{-1})$ is a metric measure space, for m a Borel measure on M .

Aim

Do the same for \mathbb{M}_n and give an upper bound on $GW_p(\bar{\mathbb{R}}, \mathbb{M}_n)$.

Mapper

We construct an injection between the Mapper (as a simplicial complex) and $C(M)$, through a map $\Delta: X_n \rightarrow \mathbb{M}_n$.

We then consider $(\mathbb{M}_n, d_H, m_n \circ \Delta^{-1})$ where m_n is the empirical measure

$$m_n = \frac{1}{n} \sum_{i=1}^n \delta_{x_i}.$$

Assumptions

We make two assumptions:

- The Ricci curvature Ric of M is lower bounded:

$$\text{Ric} \geq (d - 1) \cdot k$$

where $k \in \mathbb{R}$.

- The measure m is absolutely continuous with respect to the volume measure Vol and admits an upper bounded density, i.e.,

$$\sup \frac{dm}{d\text{Vol}} < +\infty.$$

Furthermore, we assume that m is fully supported on M .

We will assume a *homogeneous covering of resolution* $r \in \mathbb{N}$, i.e., the intervals $\mathbb{I} = \{I_1, \dots, I_r\}$ are all of the same length and consecutive intervals have a percentage $0 < g < 1/2$ of their length in common.

We call *maximal width* δ_r of the cover \mathbb{I} the maximal length of an elementary block in \mathbb{I} .

Main result

Theorem [Oulhaj et al., 2025]

Consider the two metric measure spaces $(\bar{\mathbb{R}}, d_H, m \circ \pi^{-1})$ and $(\mathbb{M}_n, d_H, m_n \circ \Delta^{-1})$ corresponding to the Reeb graph and to the Mapper graph respectively. For any $\alpha > 0$, $p \geq 1$ and a resolution $r(n)$ of the Mapper satisfying $r(n) \underset{n \rightarrow \infty}{\sim} n^{\frac{1}{d+\alpha}}$, we then have, for any large enough sample size n :

$$\mathbb{E}(\text{GW}_p(\bar{\mathbb{R}}, \mathbb{M}_n)) \lesssim n^{-\frac{\nu}{d+\alpha}}$$

where

$$\nu = \min \left\{ \frac{1}{2}, \frac{d}{p(d+1)} \right\}.$$

Estimation-Approximation bound

$$\text{GW}_\rho(\bar{\mathbb{R}}, \mathbb{M}_n) \leq E_n + A_n,$$

where

- $E_n = W_\rho(m \circ \pi^{-1}, m_n \circ \pi^{-1})$, and
- $A_n = \left(\frac{1}{n} \sum_{i=1}^n d_H([x_i]_{\sim_f}, \Delta(x_i))^\rho\right)^{\frac{1}{\rho}}$.

Introduce $(\bar{\mathbb{R}}, d_H, m_n \circ \pi^{-1})$ as an intermediate space.

Estimation term

$E_n = W_p(\mathfrak{m} \circ \pi^{-1}, \mathfrak{m}_n \circ \pi^{-1})$ is the Wasserstein distance between a measure and an associated empirical measure in a polish metric space $((\bar{\mathbb{R}}, d_H)$ here).

This has been studied in [Weed and Bach, 2019] where a sharp upper bound is given. The main ingredient is a control on the *covering number* of $(\bar{\mathbb{R}}, d_H)$.

- We relate the covering number of $(\bar{\mathbb{R}}, d_H)$ to that of M .
- We use volume comparison (Bishop-Gromov Theorem) to control the covering number of M .

Covering number for \mathbb{R}

Proposition

There exists $\varepsilon' > 0$ such that for every $\varepsilon \leq \varepsilon'$ we have

$$\mathcal{N}_\varepsilon(\mathbb{R}) \leq N_c + \left(\frac{\beta}{\varepsilon}\right)^{2d},$$

where N_c is the number of elements in \mathbb{R} associated to critical values, d is the dimension of M and β is a constant depending on f and M .

Approximation term

$A_n = \left(\frac{1}{n} \sum_{i=1}^n d_H([x_i]_{\sim_f}, \Delta(x_i))^p \right)^{\frac{1}{p}}$ is bounded explicitly.

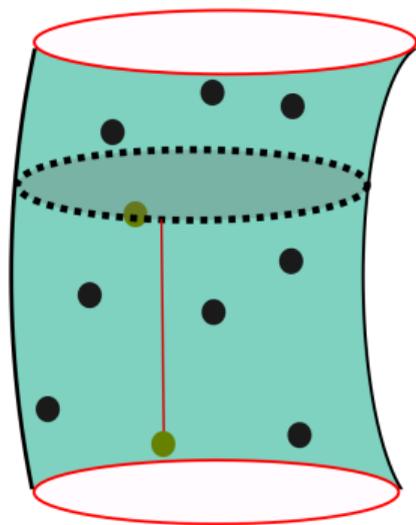
- Away from critical values, the gradient flow of f can be used.
- Otherwise...

Step 1

For any large enough resolution r and for every $x_j \in \Delta(x_i)$:

$$d(x_j, [x_i]_{\sim_f}) \leq \max_{c \in \text{Crit}(f)} \mu(c) \cdot \sqrt{\frac{1-g}{g}} \cdot \sqrt{\delta_r}$$

$\mu(c)$ is the square root of the spectral radius of the metric at c .



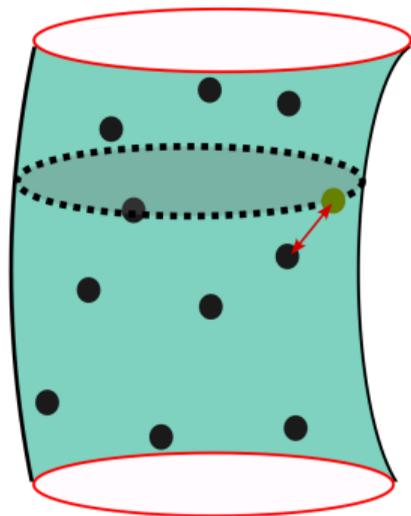
Step 2

Let $\lambda > 0$ such that $d_H(X_n, M) \leq \lambda$ and

$$\omega_f(\lambda) := \sup_{d(x,y) \leq \lambda} |f(x) - f(y)| \leq \frac{g}{1-g} \frac{\delta_r}{4}.$$

For any large enough resolution r and for every $y \in [x_i]_{\sim_f}$:

$$d(y, \Delta(x_i)) \leq \lambda + \frac{1}{2} \cdot \max_{c \in \text{Crit}(f)} \mu(c) \cdot \sqrt{\frac{1-g}{g}} \cdot \sqrt{\delta_r}.$$



Step 3

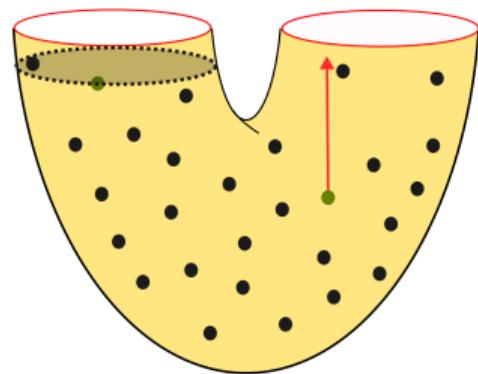
Close to critical values. We need to "bruteforce" the problem.
For any large enough resolution r , we have:

$$\max_{J \in \mathbb{J}} \text{Vol}(f^{-1}(J)) \leq \eta \cdot \delta_r^{\frac{d}{d+1}},$$

where

$$\eta = \max_{c \in \text{Crit}(f)} \mu(c)^2 \cdot \sup_{v \notin f(\text{Crit}(f))} \text{Vol}_{d-1}(f^{-1}(\{v\})) + 2\alpha_d |\text{Crit}(f)|,$$

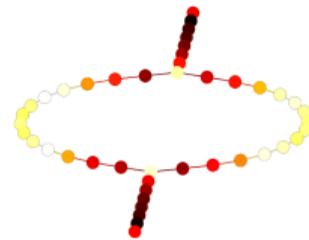
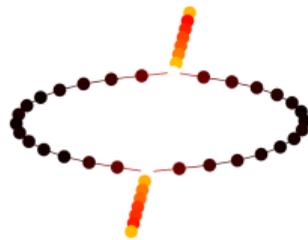
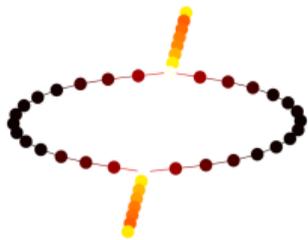
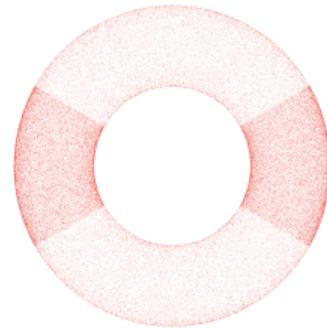
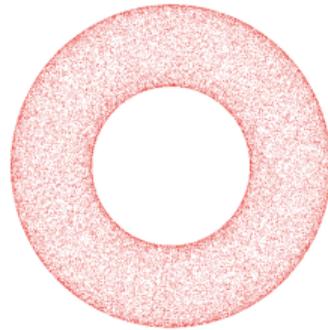
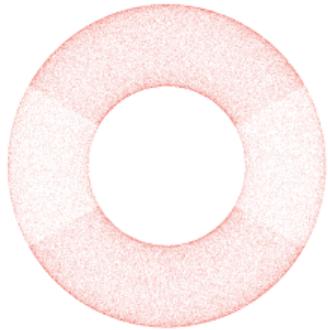
and where $\text{Vol}_{d-1}(f^{-1}(\{v\}))$ is the $(d-1)$ -dimensional volume of $f^{-1}(\{v\})$ seen as a submanifold of M and α_d is the volume of the unit ball in \mathbb{R}^d .



Unfortunately

This last step gives the slowest term that dictates the final convergence rate :(

In practice



In practice

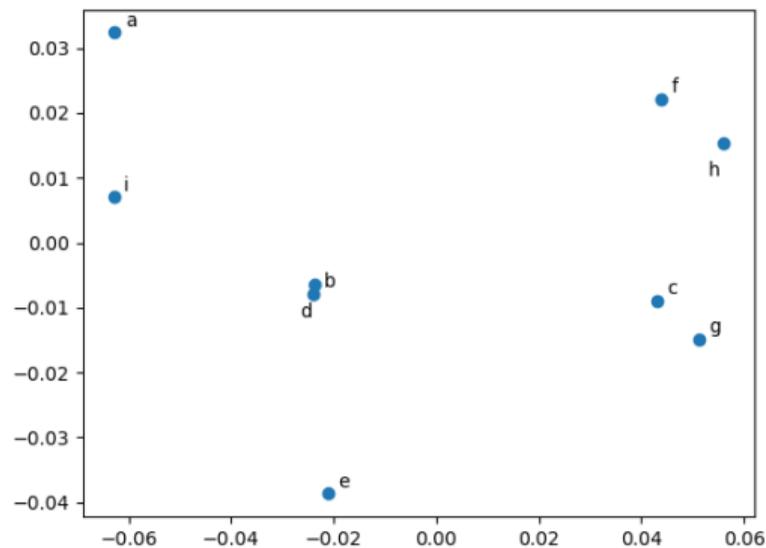


Figure: MDS visualization of the Gromov-Wasserstein distance matrix between the different Mapper graphs.

Label	left	right
a	$1/12$	$1/12$
b	$1/12$	$1/6$
c	$1/12$	$1/3$
d	$1/6$	$1/12$
e	$1/6$	$1/6$
f	$1/6$	$1/3$
g	$1/3$	$1/12$
h	$1/3$	$1/6$
i	$1/3$	$1/3$

Table: Correspondence between the labels and the parameters of the measure.

Thank you for listening !

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